Review: Direct-mapped caches

- If the cache contains $2^k$ bytes, then the k least significant bits (LSBs) are used as the index.
  - data from address $i$ would be stored in block $i \mod 2^k$.

- For example, data from memory address 11 maps to cache block 3 on the right, since $11 \mod 4 = 3$ and since the lowest two bits of 1011 are 11.
To find data stored in the cache, we need to add tags to distinguish between different memory locations that map to the same cache block.

We include a single valid bit per block to distinguish full and empty blocks.
Review: How big is the cache?

For a byte-addressable machine with 16-bit addresses with a cache with the following characteristics:

- It is direct-mapped (as discussed last time)
- Each block holds one byte
- The cache index is the four least significant bits

Two questions:

- How many blocks does the cache hold?
- How many bits of storage are required to build the cache (e.g., for the data array, tags, valid)?
Review: How big is the cache?

For a byte-addressable machine with 16-bit addresses with a cache with the following characteristics:

- It is direct-mapped (as discussed last time)
- Each block holds one byte
- The cache index is the four least significant bits

Two questions:

- How many blocks does the cache hold?
  
  4-bit index $\rightarrow 2^4 = 16$ blocks

- How many bits of storage are required to build the cache (e.g., for the data array, tags, etc.)?
  
  tag size = 12 bits (16 bit address - 4 bit index)
  
  $(12$ tag bits $+ 1$ valid bit $+ 8$ data bits) $\times 16$ blocks $= 21$ bits $\times 16 = 336$ bits
Today, we’ll explore some alternate cache organizations.

- How can we take advantage of spatial locality too?
- How can we reduce the number of potential conflicts?
Memory System Performance

- To examine the performance of a memory system, we need to focus on a couple of important factors.
  - How long does it take to send data from the cache to the CPU?
  - How long does it take to copy data from memory into the cache?
  - How often do we have to access main memory?

- There are names for all of these variables.
  - The **hit time** is how long it takes data to be sent from the cache to the processor. This is usually fast, on the order of 1-3 clock cycles.
  - The **miss penalty** is the time to copy data from main memory to the cache. This often requires dozens of clock cycles (at least).
  - The **miss rate** is the percentage of misses.
The average memory access time, or AMAT, can then be computed.

$$\text{AMAT} = \text{Hit time} + (\text{Miss rate} \times \text{Miss penalty})$$

This is just averaging the amount of time for cache hits and the amount of time for cache misses.

How can we improve the average memory access time of a system?

- Obviously, a lower AMAT is better.
- Miss penalties are usually much greater than hit times, so the best way to lower AMAT is to reduce the miss penalty or the miss rate.

However, AMAT should only be used a general guideline. Remember that execution time is still the best performance metric.
Performance example

- Assume the cache hit ratio is 97% and the hit time is one cycle, but the miss penalty is 20 cycles.

\[
\text{AMAT} = \text{Hit time} + (\text{Miss rate} \times \text{Miss penalty})
\]

- How can we reduce miss rate?
Performance example

- Assume the cache hit ratio is 97% and the hit time is one cycle, but the miss penalty is 20 cycles.

\[
AMAT = \text{Hit time} + (\text{Miss rate} \times \text{Miss penalty})
= 1 \text{ cycle} + (3\% \times 20 \text{ cycles})
= 1.6 \text{ cycles}
\]

- If the cache was perfect and never missed, the AMAT would be one cycle. But even with just a 3% miss rate, the AMAT here increases 1.6 times!

- How can we reduce miss rate?
Spatial locality

- One-byte cache blocks don’t take advantage of spatial locality, which predicts that an access to one address will be followed by an access to a nearby address.

- What can we do?
What we can do is make the cache block size larger than one byte.

Here we use two-byte blocks, so we can load the cache with two bytes at a time.

If we read from address 12, the data in addresses 12 and 13 would both be copied to cache block 2.
Now how can we figure out where data should be placed in the cache?

It’s time for block addresses! If the cache block size is \(2^n\) bytes, we can conceptually split the main memory into \(2^n\)-byte chunks too.

To determine the block address of a byte address \(i\), you can do the integer division

\[
i / 2^n
\]

Our example has two-byte cache blocks, so we can think of a 16-byte main memory as an “8-block” main memory instead.

For instance, memory addresses 12 and 13 both correspond to block address 6, since \(12 / 2 = 6\) and \(13 / 2 = 6\).
Once you know the block address, you can map it to the cache as before: find the remainder when the block address is divided by the number of cache blocks.

In our example, memory block 6 belongs in cache block 2, since $6 \mod 4 = 2$.

This corresponds to placing data from memory byte addresses 12 and 13 into cache block 2.
When we access one byte of data in memory, we’ll copy its entire block into the cache, to hopefully take advantage of spatial locality.

In our example, if a program reads from byte address 12 we’ll load all of memory block 6 (both addresses 12 and 13) into cache block 2.

Note byte address 13 corresponds to the same memory block address! So a read from address 13 will also cause memory block 6 (addresses 12 and 13) to be loaded into cache block 2.

To make things simpler, byte $i$ of a memory block is always stored in byte $i$ of the corresponding cache block.
Let’s say we have a cache with $2^k$ blocks, each containing $2^n$ bytes.

We can determine where a byte of data belongs in this cache by looking at its address in main memory.

- $k$ bits of the address will select one of the $2^k$ cache blocks.
- The lowest $n$ bits are now a block offset that decides which of the $2^n$ bytes in the cache block will store the data.

Our example used a $2^2$-block cache with $2^1$ bytes per block. Thus, memory address 13 (1101) would be stored in byte 1 of cache block 2.
A picture
An exercise

For the addresses below, what byte is read from the cache (or is there a miss)?

1010
1110
0001
1101
An exercise

For the addresses below, what byte is read from the cache (or is there a miss)?

- 1010  (0xDE)
- 1110  (miss, invalid)
- 0001  (0xFE)
- 1101  (miss, bad tag)
Using arithmetic

- An equivalent way to find the right location within the cache is to use arithmetic again.

- We can find the index in two steps, as outlined earlier.
  - Do integer division of the address by $2^n$ to find the block address.
  - Then mod the block address with $2^k$ to find the index.

- The block offset is just the memory address mod $2^n$.

- For example, we can find address 13 in a 4-block, 2-byte per block cache.
  - The block address is $13 / 2 = 6$, so the index is then $6 \mod 4 = 2$.
  - The block offset would be $13 \mod 2 = 1$. 
Here is a cache with 1,024 blocks of 4 bytes each, and 32-bit memory addresses.
A larger example cache mapping

Where would the byte from memory address 6146 be stored in this direct-mapped $2^{10}$-block cache with $2^2$-byte blocks?

We can determine this with the binary force.

- 6146 in binary is 00...01 1000 0000 00 10.
- The lowest 2 bits, 10, mean this is the second byte in its block.
- The next 10 bits, 1000000000, are the block number itself (512).

Equivalently, you could use your arithmetic instead.

- The block offset is 6146 mod 4, which equals 2.
- The block address is 6146/4 = 1536, so the index is 1536 mod 1024, or 512.
A larger diagram of a larger example cache mapping

<table>
<thead>
<tr>
<th>Index</th>
<th>Valid</th>
<th>Tag</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>...</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>512</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>...</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1022</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1023</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Address (32 bits)

\[
\begin{array}{c|c|c}
0000 \ldots & 0001 & 1000000000 \\
\end{array}
\]

2 bits

`Address (32 bits)`

20

10

Index

Valid

Tag

Data

Tag

Hit

Mux

Data

8

8

8

8
What goes in the rest of that cache block?

- The other three bytes of that cache block come from the same memory block, whose addresses must all have the same index (1000000000) and the same tag (00...01).

![Diagram of cache memory organization]
Again, byte $i$ of a memory block is stored into byte $i$ of the corresponding cache block.

- In our example, memory block 1536 consists of byte addresses 6144 to 6147. So bytes 0-3 of the cache block would contain data from address 6144, 6145, 6146 and 6147 respectively.
- You can also look at the lowest 2 bits of the memory address to find the block offsets.

<table>
<thead>
<tr>
<th>Block offset</th>
<th>Memory address</th>
<th>Decimal</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>00..01 1000000000 00</td>
<td>6144</td>
</tr>
<tr>
<td>01</td>
<td>00..01 1000000000 01</td>
<td>6145</td>
</tr>
<tr>
<td>10</td>
<td>00..01 1000000000 10</td>
<td>6146</td>
</tr>
<tr>
<td>11</td>
<td>00..01 1000000000 11</td>
<td>6147</td>
</tr>
</tbody>
</table>

Index | Valid | Tag | Data
---|-------|-----|-----
... |       |     |     |
512 |       |     |     |
... |       |     |     |
Disadvantage of direct mapping

- The direct-mapped cache is easy: indices and offsets can be computed with bit operators or simple arithmetic, because each memory address belongs in exactly one block.

- But, what happens if a program uses addresses 2, 6, 2, 6, 2, …?

```
Memory Address
0000
0001
0010
0011
0100
0101
0110
0111
1000
1001
1010
1011
1100
1101
1110
1111
```

```
Index
00
01
10
11
```
Disadvantage of direct mapping

- The direct-mapped cache is easy: indices and offsets can be computed with bit operators or simple arithmetic, because each memory address belongs in exactly one block.

- However, this isn’t really flexible. If a program uses addresses 2, 6, 2, 6, 2, ..., then each access will result in a cache miss and a load into cache block 2.

- This cache has four blocks, but direct mapping might not let us use all of them.

- This can result in more misses than we might like.
A fully associative cache

- A fully associative cache permits data to be stored in *any* cache block, instead of forcing each memory address into one particular block.
  - When data is fetched from memory, it can be placed in *any* unused block of the cache.
  - This way we’ll never have a conflict between two or more memory addresses which map to a single cache block.

- In the previous example, we might put memory address 2 in cache block 2, and address 6 in block 3. Then subsequent repeated accesses to 2 and 6 would all be hits instead of misses.

- If all the blocks are already in use, it’s usually best to replace the least recently used one, assuming that if it hasn’t been used it in a while, it won’t be needed again anytime soon.
The price of full associativity

However, a fully associative cache is expensive to implement.

- Because there is no index field in the address anymore, the entire block address must be used as the tag, increasing the total cache size.
- Data could be anywhere in the cache, so we must check the tag of every cache block. That’s a lot of comparators!

<table>
<thead>
<tr>
<th>Address (32 bits)</th>
<th>Index</th>
<th>Valid</th>
<th>Tag (32 bits)</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Diagram:

- Address: 32 bits
- Tag: 32 bits
- Index
- Valid
- Data
- Hit

Comparators for each tag check.
Set associativity

- An intermediate possibility is a set-associative cache.
  - The cache is divided into groups of blocks, called sets.
  - Each memory address maps to exactly one set in the cache, but data may be placed in any block within that set.
- If each set has x blocks, the cache is an x-way associative cache.
- Here are several possible organizations of an eight-block cache.
2-way set associative cache implementation

- How does an implementation of a 2-way cache compare with that of a fully-associative cache?
- Only two comparators are needed.
- The cache tags are a little shorter too.
Locating a set associative block

- We can determine where a memory address belongs in an associative cache in a similar way as before.
- If a cache has $2^s$ sets and each block has $2^n$ bytes, the memory address can be partitioned as follows.

  Our arithmetic computations now compute a set index, to select a set within the cache instead of an individual block.

  \[
  \begin{align*}
  \text{Block Offset} &= \text{Memory Address mod } 2^n \\
  \text{Block Address} &= \text{Memory Address} / 2^n \\
  \text{Set Index} &= \text{Block Address mod } 2^s
  \end{align*}
  \]
Set associative caches are a general idea

- By now you may have noticed the 1-way set associative cache is the same as a direct-mapped cache.
- Similarly, if a cache has \(2^k\) blocks, a \(2^k\)-way set associative cache would be the same as a fully-associative cache.
Example placement in set-associative caches

- Where would data from memory byte address 6195 be placed, assuming the eight-block cache designs below, with 16 bytes per block?
- 6195 in binary is 00...0110000 011 0011.
- Each block has 16 bytes, so the lowest 4 bits are the block offset.
- For the 1-way cache, the next three bits (011) are the set index.
  For the 2-way cache, the next two bits (11) are the set index.
  For the 4-way cache, the next one bit (1) is the set index.
- The data may go in any block, shown in green, within the correct set.

1-way associativity
8 sets, 1 block each

2-way associativity
4 sets, 2 blocks each

4-way associativity
2 sets, 4 blocks each
Block replacement

- Any empty block in the correct set may be used for storing data.
- If there are no empty blocks, the cache controller will attempt to replace the least recently used block, just like before.
- For highly associative caches, it’s expensive to keep track of what’s really the least recently used block, so some approximations are used. We won’t get into the details.

1-way associativity
8 sets, 1 block each

2-way associativity
4 sets, 2 blocks each

4-way associativity
2 sets, 4 blocks each
LRU example

- Assume a fully-associative cache with two blocks, which of the following memory references miss in the cache.
  - Assume distinct addresses go to distinct blocks

<table>
<thead>
<tr>
<th>Addresses</th>
<th>0</th>
<th>Tags</th>
<th>1</th>
<th>LRU</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>--</td>
<td>--</td>
<td></td>
<td>0</td>
</tr>
<tr>
<td>B</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>C</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>B</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>B</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
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LRU example

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<table>
<thead>
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<th>Tags</th>
<th>LRU</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>--</td>
<td>0</td>
</tr>
<tr>
<td>miss A</td>
<td>--</td>
<td>0</td>
</tr>
<tr>
<td>miss B</td>
<td>A</td>
<td>1</td>
</tr>
<tr>
<td>miss B</td>
<td>A B</td>
<td>0</td>
</tr>
<tr>
<td>miss C</td>
<td>A B</td>
<td>1</td>
</tr>
<tr>
<td>miss B</td>
<td>A C</td>
<td>0</td>
</tr>
<tr>
<td>miss A</td>
<td>B C</td>
<td>1</td>
</tr>
<tr>
<td>miss A</td>
<td>B A</td>
<td>0</td>
</tr>
<tr>
<td>miss B</td>
<td>B A</td>
<td>1</td>
</tr>
</tbody>
</table>

On a miss, we replace the LRU.

On a hit, we just update the LRU.
Exercise

Assume you have a fully associative cache with 4 entries. For the following memory block address sequence, which entry becomes the LRU at the end?

8 9 5 2 6 5 9 10 3
Mind twist

- Can we have odd number of blocks in a set?
Exercise

- For a 64KB cache, how do you organize it for a direct mapped cache? What about 2-way set associative cache?

- 96KB cache?
Summary

- Larger block sizes can take advantage of spatial locality by loading data from not just one address, but also nearby addresses, into the cache.

- Associative caches assign each memory address to a particular set within the cache, but not to any specific block within that set.
  - Set sizes range from 1 (direct-mapped) to $2^k$ (fully associative).
  - Larger sets and higher associativity lead to fewer cache conflicts and lower miss rates, but they also increase the hardware cost.
  - In practice, 2-way through 16-way set-associative caches strike a good balance between lower miss rates and higher costs.