

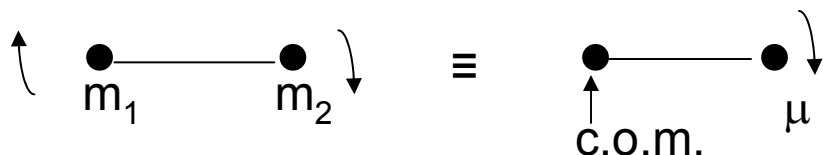
# Chapter 7, continued

## Rotation in 2 dimensions

$$H_{\text{total}} = H_{\text{trans}}(r_{\text{cm}}) + H_{\text{vib}}(\tau_{\text{internal}}) + H_{\text{rot}}(\theta, \phi)$$

$$E_{\text{total}} = E_{\text{trans}} + E_{\text{vib}} + E_{\text{rot}}$$

$$\Psi_{\text{tot}} = \Psi_{\text{trans}} \Psi_{\text{vib}} \Psi_{\text{rot}}$$



$V(x,y) = 0$  everywhere

$$-\frac{\hbar^2}{2\mu} \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)_{r=r_0} = E\psi$$

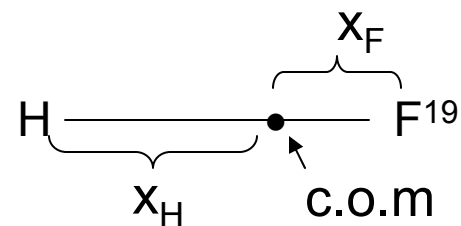
↑  
fixed  
radius

reduced mass

$$\frac{1}{\mu} = \frac{1}{m_1} = \frac{1}{m_2}$$

$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

separation of variables



$$x_H + x_F = .9168 \text{ \AA}$$

$$x_H m_H = x_F m_F$$

$$x_F = .0458 \text{ \AA}$$

$$x_H = .8710 \text{ \AA}$$

Switch to polar coordinates:  $(x,y) \rightarrow (r, \phi)$

$$\frac{-\hbar^2}{2\mu r_0^2} \frac{d^2\Phi}{d\phi^2} = E\Phi \longrightarrow \Phi = e^{im\phi}, \quad m = 0, \pm 1, \pm 2, \dots$$
$$0 \leq \phi \leq 2\pi$$

$$e^{im(\phi+2\pi)} = e^{im\phi} \implies e^{im2\pi} = 1$$

$$e^{im2\pi} = \cos 2\pi m + i \sin 2\pi m = 1 \implies m = 0, \pm 1, \pm 2, \dots$$

$$E = \frac{\hbar^2 m^2}{2\mu r_0^2} = \frac{\hbar^2 m^2}{2I} \quad I = \mu r_0^2 = \text{moment of inertia}$$

quantization due to boundary condition  $\Phi(0) = \Phi(2\pi)$

Note: there is no zero-point energy. Why?

Classically  $E = \frac{|\vec{\ell}|^2}{2I} = \frac{1}{2} I \omega^2$  | All energies possible  
 $\vec{\ell} =$  angular momentum

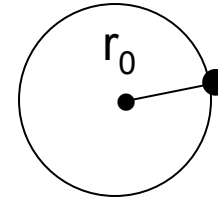
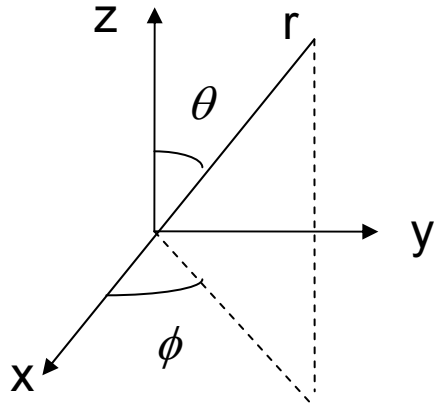
angular momentum in z direction:  $\vec{\ell}_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}$

$$\vec{\ell}_z \Phi = \frac{\hbar}{i} \frac{1}{\sqrt{2\pi}} \frac{d}{d\phi} e^{im\phi} = m\hbar \Phi$$

$P(\phi)d\phi = \frac{d\phi}{2\pi}$ , all  $\phi$  values equally probable  
angular momentum in z direction  
precisely defined

$\vec{\ell}_z, \hat{\phi}$  do **not** commute

On to 3 dimensions:  $(x, y, z) \rightarrow (r, \theta, \phi)$



motion of particle on  
the surface of a sphere

$\equiv$  Rigid rotor

$$\left. \begin{array}{l} 0 \leq r \leq \infty \\ 0 \leq \theta \leq \pi \\ 0 \leq \phi \leq 2\pi \end{array} \right\}$$

volume element  $r^2 \sin \theta dr d\theta d\phi$

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

$$\frac{-\hbar^2}{2\mu r_0^2} \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 Y}{\partial \phi^2} \right] = EY$$

$Y(\theta, \phi) = \text{wave function}$

$$\beta = \frac{\partial \mu r_0^2}{\hbar^2} E$$

$$\underbrace{\sin \theta \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y}{\partial \theta} \right) + \beta \sin^2 \theta Y}_{\text{depends only on } \theta} = \underbrace{-\frac{\partial^2 Y}{\partial \phi^2}}_{\text{depends only on } \phi}$$

$$\Rightarrow Y(\theta, \phi) = \Theta(\theta)\Phi(\phi)$$

separation of variables  
spherical harmonics

$$\underbrace{\frac{1}{\Theta} \sin \theta \frac{d}{d\theta} \left( \sin \theta \frac{d\Theta}{d\theta} \right) + \beta \sin^2 \theta}_{\text{depends only on } \theta} = \underbrace{\frac{-1}{\Phi} \frac{d^2 \Phi}{d\phi^2}}_{\text{depends only on } \phi}$$

$\Rightarrow$  this must be equal to a constant