

## SOLUTION MANUAL FOR HW # 7

### 9.2

$$E_n = -\frac{e^2}{8\pi\epsilon_0 a_0 n^2}$$

$$a.E = -\frac{e^2}{32\pi\epsilon_0 a_0} \Rightarrow n = 2 \Rightarrow l = 0,1 \Rightarrow m_l = 0, \pm 1 \Rightarrow \psi_{200}, \psi_{210}, \psi_{21\pm 1}$$

$$b.E = -\frac{e^2}{72\pi\epsilon_0 a_0} \Rightarrow n = 3 \Rightarrow l = 0,1,2 \Rightarrow m_l = 0, \pm 1, \pm 2 \Rightarrow \psi_{300}, \psi_{310}, \psi_{31\pm 1}, \psi_{320}, \psi_{32\pm 1}, \psi_{32\pm 2}$$

$$c.E = -\frac{e^2}{128\pi\epsilon_0 a_0} \Rightarrow n = 4 \Rightarrow l = 0,1,2,3 \Rightarrow m_l = 0, \pm 1, \pm 2, \pm 3 \Rightarrow \psi_{400}, \psi_{410}, \psi_{41\pm 1}, \psi_{420}, \psi_{42\pm 1},$$

$$\psi_{42\pm 2}, \psi_{430}, \psi_{43\pm 1}, \psi_{43\pm 2}, \psi_{43\pm 3}$$

*Degeneracy :*

a.4   b.9   c.16

### 9.4

$$\psi_{210} = \frac{1}{2\sqrt{6}} a_0^{-3/2} (a_0^{-1} r) e^{-a_0^{-1} r/2} \cos \theta$$

$$\psi_{211} = \frac{1}{2\sqrt{6}} a_0^{-3/2} (a_0^{-1} r) e^{-a_0^{-1} r/2} \sin \theta e^{i\varphi}$$

$$\int_0^\pi \int_0^{2\pi} \int_0^\infty \psi_{210} \psi_{211} d\tau = \frac{1}{24} \int_0^r a_0^{-5} r^4 e^{-a_0^{-1} r} dr \int_0^\pi \cos \theta \sin^2 \theta d\theta \int_0^{2\pi} e^{i\varphi} d\varphi = 0$$

$$\therefore \sin \theta = u \quad \& \quad \cos \theta d\theta = du$$

$$\Rightarrow \int_0^\pi \cos \theta \sin^2 \theta d\theta = \int_{\theta=0}^{\theta=\pi} u^2 du = \frac{u^3}{3} \Big|_{\theta=0}^{\theta=\pi} = \frac{\sin^3 \theta}{3} \Big|_0^\pi = 0$$

$$\therefore e^{i\varphi} = \cos \varphi + i \sin \varphi$$

$$\int_0^{2\pi} e^{i\varphi} d\varphi = \int_0^{2\pi} (\cos \varphi + i \sin \varphi) d\varphi = (\sin \varphi - i \cos \varphi) \Big|_0^{2\pi} = 0$$

### 9.6

- a. n=2 & l=1 → Angular node=1 & 2-1-1=0 Radial node
- b. n=2 & l=0 → Angular node=0 & 2-0-1=1 Radial node
- c. n=3 & l=2 → Angular node=2 & 3-2-1=0 Radial node
- d. n=3 & l=2 → Angular node=2 & 3-2-1=0 Radial node

### 9.11

$$\begin{aligned}
\langle r \rangle &= \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* r \psi_{100} r^2 \sin \theta dr d\theta d\varphi \\
\langle r \rangle &= \int_0^\infty \int_0^\pi \int_0^{2\pi} \frac{1}{\sqrt{\pi}} a_0^{-3/2} e^{-a_0^{-1}r} r^3 \frac{1}{\sqrt{\pi}} a_0^{-3/2} e^{-a_0^{-1}r} \sin \theta dr d\theta d\varphi \\
\langle r \rangle &= \frac{a_0^{-3}}{\pi} \left( \int_0^\infty r^3 e^{-2a_0^{-1}r} dr \right) \left( \int_0^\pi \sin \theta d\theta \int_0^{2\pi} d\varphi \right) = 4a_0^{-3} \int_0^\infty r^3 e^{-2a_0^{-1}r} dr = 4a_0^{-3} \frac{3!}{(2a_0^{-1})^{3+1}} = \frac{3}{2} a_0
\end{aligned}$$

**9.17**



$$\psi_{100} = \frac{1}{\sqrt{\pi}} a_0^{-3/2} e^{-a_0^{-1}r}$$

$$\langle z \rangle = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* z \psi_{100} r^2 \sin \theta dr d\theta d\varphi = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* r \cos \theta \psi_{100} r^2 \sin \theta dr d\theta d\varphi$$

$$\langle z \rangle = \frac{3}{4a_0^{-1}} \int_0^\pi \cos \theta \sin \theta d\theta = \frac{3}{8a_0} \sin 2\theta \Big|_0^\pi = 0$$

$$\langle z^2 \rangle = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* z^2 \psi_{100} r^2 \sin \theta dr d\theta d\varphi = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* r^2 \cos^2 \theta \psi_{100} r^2 \sin \theta dr d\theta d\varphi$$

$$\langle z^2 \rangle = \frac{3}{2a_0^{-2}} \int_0^\pi \cos^2 \theta \sin \theta d\theta = \frac{3}{2a_0^{-2}} \left( -\frac{\cos^3 \theta}{3} \right) \Big|_0^\pi = a_0^2$$

$$\langle x \rangle = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* x \psi_{100} r^2 \sin \theta dr d\theta d\varphi = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* r \sin \theta \cos \varphi \psi_{100} r^2 \sin \theta dr d\theta d\varphi$$

$$\langle x \rangle = \frac{3}{8\pi a_0^{-1}} \int_0^\pi \sin \theta \sin \theta d\theta \int_0^{2\pi} \cos \varphi d\varphi = \frac{3}{8\pi a_0^{-1}} \cdot \frac{\pi}{2} \cdot 0 = 0$$

$$\langle x^2 \rangle = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* x^2 \psi_{100} r^2 \sin \theta dr d\theta d\varphi = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* r^2 \sin^2 \theta \cos^2 \varphi \psi_{100} r^2 \sin \theta dr d\theta d\varphi$$

$$\langle x^2 \rangle = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \int_0^\pi \sin^2 \theta \sin \theta d\theta \int_0^{2\pi} \cos^2 \varphi d\varphi = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \int_0^\pi (1 - \cos^2 \theta) \sin \theta d\theta \int_0^{2\pi} \cos^2 \varphi d\varphi$$

$$\langle x^2 \rangle = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \int_0^\pi (1 - u^2) - du \int_0^{2\pi} \frac{1}{2} (\cos 2\varphi + 1) d\varphi = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \left( \frac{u^3}{3} - u \right) \Big|_1^{-1} \left( \frac{\sin 2\varphi}{4} + \frac{\varphi}{2} \right) \Big|_0^{2\pi} =$$

$$\langle x^2 \rangle = \frac{4! a_0^{-3}}{(2a_0^{-1})^{4+1} \pi} \cdot \frac{4}{3} \cdot \pi = a_0^2$$

$$\langle y \rangle = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* y \psi_{100} r^2 \sin \theta dr d\theta d\varphi = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* r \sin \theta \sin \varphi \psi_{100} r^2 \sin \theta dr d\theta d\varphi$$

$$\langle x \rangle = \frac{3}{8\pi a_0^{-1}} \int_0^\pi \sin \theta \sin \theta d\theta \int_0^{2\pi} \sin \varphi d\varphi = \frac{3}{8\pi a_0^{-1}} \cdot \frac{\pi}{2} \cdot 0 = 0$$

$$\langle y^2 \rangle = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* y^2 \psi_{100} r^2 \sin \theta dr d\theta d\varphi = \int_0^\infty \int_0^\pi \int_0^{2\pi} \psi_{100}^* r^2 \sin^2 \theta \sin^2 \varphi \psi_{100} r^2 \sin \theta dr d\theta d\varphi$$

$$\langle y^2 \rangle = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \int_0^\pi \sin^2 \theta \sin \theta d\theta \int_0^{2\pi} \sin^2 \varphi d\varphi = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \int_0^\pi (1 - \cos^2 \theta) \sin \theta d\theta \int_0^{2\pi} \sin^2 \varphi d\varphi$$

$$\langle y^2 \rangle = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \int_0^\pi (1 - u^2) - du \int_0^{2\pi} \frac{1}{2} (1 - \cos 2\varphi) d\varphi = \frac{4!}{(2a_0^{-1})^{4+1} \pi} \left( \frac{u^3}{3} - u \right) \Big|_1^{-1} \left( \frac{\varphi}{2} - \frac{\sin 2\varphi}{4} \right) \Big|_0^{2\pi} =$$

$$\langle y^2 \rangle = \frac{4! a_0^{-3}}{(2a_0^{-1})^{4+1} \pi} \cdot \frac{4}{3} \cdot \pi = a_0^2$$

$$\langle x \rangle = \langle y \rangle = \langle z \rangle = 0 \quad \& \quad \langle x^2 \rangle = \langle y^2 \rangle = \langle z^2 \rangle = a_0^2$$